

# Perceived realism has a significant impact on presence

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## Context

- Several authors have examined factors that are related to a stronger feeling of presence.
  - Field of view (*Lin et al., 2002; Prothero et al., 1995*)
  - Stereoscopia (*Ijsselstein et al., 2001*)
  - Sound / spatialized sound (*Hendrix & Barfield, 1996*)
  - Tactile augmentation (*Hoffman et al., 1996, 1998*)

## Pictorial realism, delay, interactivity.

*Welch et al., (1996).*

- Two studies with CRT projectors and poor quality VE (by current standards). Driving simulation. University students. Repeated immersions in different experimental conditions
- Study 1 (S1):
  - Interactivity (driver/high or passenger/low)
  - Realism (low = black sky, black background, no oncoming cars, etc.)
- Study 2 (S2):
  - Delay in visual feedback (normal/200ms or 1.5 sec)
  - Realism
- There were significant differences for all three variables.
- When asked what was more important, participants chose Interactivity over Realism (S1) and Delay over Realism (S2).

## FoV versus level of details

*(Shim & Kim, 2004).*

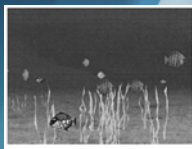
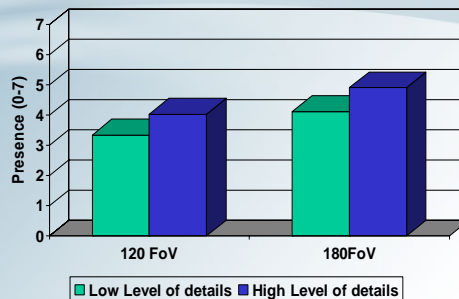


Figure 1. Screenshot of the virtual fish tank.



Figure 2. The wide display system with an adjustable FOV (FOV is adjusted only near the far end of the FOV).



### ANOVA

FoV:  $F=6.89, p < .01$

Lev of Det:  $F=25.58, p < .001$

FoV x LoD:  $F=1.68, ns.$

N = 23 engineering students

In fact, 2 additional conditions at 150 FoV.

Presence measure with one-item question.

**FoV seems more important than LoD.**

# Anxiety and image quality

Zimmons, 2004 (Ph.D. dissertation, in preparation)

Heart rate

Text -/ light +

ANOVA N = 42 :

• Time:  $p < .001$  Group:  $p < .05$  Gr X T : ns

Contrasts :

• Pre vs PIT :  $p < .001$  PIT vs post :  $p < .001$

Condition 3 vs others : All  $p < .001$

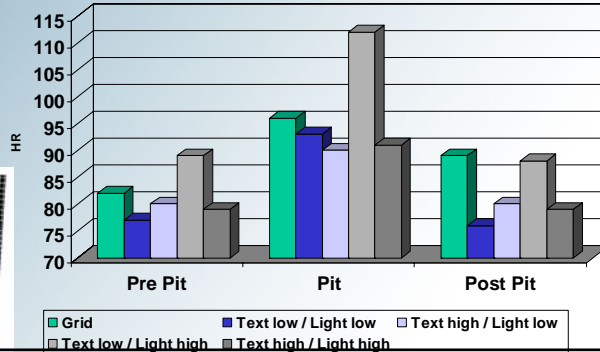
Grid vs the others: All ns.

Presence : « SUS » at post: ns Effect size = .05

Text +/ light -

Text -/ light -

Grid



## Aim

- Every study focused on the objective properties of the virtual environment that can increase realism.
- We wanted to focus on perceived realism. We therefore experimentally manipulate perceived realism.
- Our hypothesis was that presence would increase when subjects were lead to believe that the virtual environment represented a physical (“real”) environment.

## Participants

- 37 participants aged between 18 et 62 (M=33.1; sd = 15.0)
  - 11 participants were diagnosed as suffering from rodent phobia (rats / mice).
  - 26 were “diagnosed” as not suffering from rodent phobia
- Gender: 78.4 % female
- Randomly assigned to :
  - The experimental condition
    - Participants were falsely lead to believe they will be immersed in live in 3D, in real time, in a real room with a real mouse in a cage.
  - The control condition
    - Participants were told the immersion will take place in a VR environment that is a replica of a real room.

## Procedures

Step 1 : Pre-screening, SCID, informed consent



Step 2 : General assessment  
(Phobia severity, ITQ, SSQ-pre)



Step 3: Preliminary immersion

(an initial immersion in a neutral / irrelevant VE to learn how to navigate and what is presence)

## VR environment for the neutral / irrelevant immersion



## Procedures

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(an initial immersion in a neutral / irrelevant VE to learn how to navigate and what is presence)



Step 4: A brief measure of presence




Step 5: Experimental manipulation

*Control:* watching a video of a mouse in a cage




*Experimental:* discussing in videoconference with an assistant who is showing a mouse in a cage. The videoconference and VR systems are linked


## Set up




Two videoconference units linked at 384 kbps/sec




The live mouse



IBM Pentium IV™,  
ATI de 128 MB, Cy-Visor HMD,  
Intertrax²

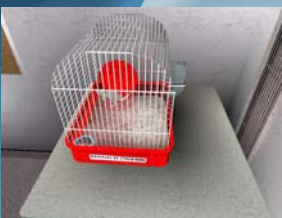





The HMD was covered with a 30 cm by 40 cm black cloth



Many computers falsely linked to the videoconference unit to create the illusion that the VR environment is a live feed from the videoconference system.

## VR environment for the experimental immersion

For the experimental immersion, this environment was a replica of the room seen in videoconference and on the video →

## Procedures

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Step 3: Preliminary immersion

(an initial immersion in a neutral / irrelevant VE to learn how to navigate and what is presence)



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*Control:* watching a video of a mouse in a cage



*Experimental:* discussing in videoconference with an assistant who is showing a mouse in a cage. The videoconference and VR systems are linked

Step 6 : A VR Immersion in the same environment

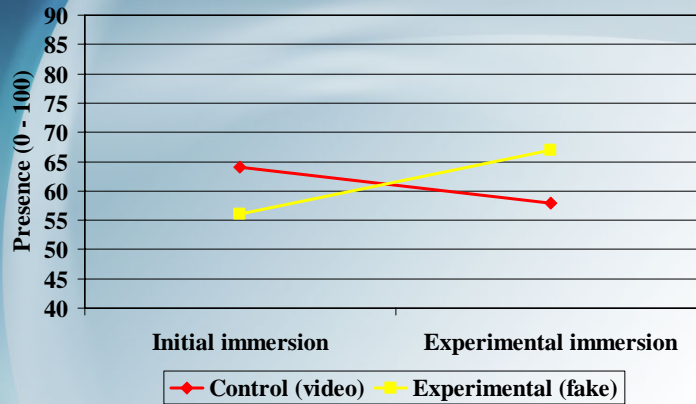


Step 7 : Post immersion measures  
Presence, SSQ

## Manipulation check

- 82% of the participants in the experimental (fake) condition believed they were actually « in » the physical room through the VR system.
- The mouse was rated as realistic by 81% of the participants in the experimental (fake) condition and by 77% of the participants in the control condition (video) (Chi-square ns).

## Result on the brief measure of presence



Within effect :  $F(1, 26) = .58, ns$   
 Between effect :  $F(1, 26) = .0, ns$   
 Interaction Within X Between :  $F(1, 26) = 6.82, p < .025$

## Results on other measures

	Control (video)		Experimental (fake)		$F_{Interaction}$
	Initial	Experi-mental	Initial	Experi-mental	
Presence Q. (W&S)	90.67 (10.19)	96.67 (15.60)	76.60 (12.13)	80.80 (14.41)	.1
SSQ	12.05 (10.07)	14.34 (15.78)	12.32 (10.97)	16.50 (15.37)	.01
Cybersickness (0-100)	9.06 (11.61)	11.56 (18.79)	21.67 (20.73)	13.40 (12.92)	2.99



## Conclusion

- These results show that perceived realism has a significant impact on presence.
- To suspend disbelief we are not limited to physical and objective qualities of the immersion in VR.
- It has been shown that emotions felt during the immersion, as well as the narrative provided before the immersion can play a significant role. Perceived realism may be another element we can manipulate.
- It is necessary to compare perceived realism and objective realism, and to reproduce this experiment with different VR scenarios.